

BACKGROUND OF THE INVENTION

Field of the Invention

Description of the Related Art

20 When transmitting an image signal according to the
Recommendation V.34, the image communication apparatus
on the calling side (hereinafter referred to as "calling
terminal") must transmit either a PPh signal or Sh signal
at the beginning of a control channel. The PPh signal
25 is used when the communication speed of the next primary
channel is negotiated under the exchange protocol of the
control signal. On the other hand, the Sh signal is used
when the communication speed of the next primary channel

need not be negotiated because the communication speed of the next primary channel is already determined.

When an image signal according to the Recommendation V.34 is received, the image communication apparatus on the answering side (hereinafter referred to as "answering terminal") must identify whether the signal received at the beginning of the control channel is a PPh signal or Sh signal. When a PPh signal is received, the answering terminal sends back a PPh signal at the beginning of the next control channel. On the other hand, when an Sh signal is received, the answering terminal sends back an Sh signal or PPh signal at the beginning of the next control channel. Therefore, the calling terminal also needs to identify whether the answering terminal sends an Sh signal or PPh signal at the beginning of the control channel.

FIG.1A shows a case where the calling terminal (TX) is sending an Sh signal at the beginning of the control channel and the answering terminal (RX) is sending back an Sh signal in response to this. On the other hand, FIG.1B shows a case where the calling terminal (TX) is sending a PPh signal at the beginning of the control channel and the answering terminal (RX) is sending back a PPh signal in response to this.

The Recommendation V.34 uses a quadrature amplitude modulation system (e.g., QAM modulation system) as one of modulation systems of control signals (PPh signal, Sh signal, etc.) exchanged on a control

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channel. FIG.2A shows a signal space diagram (IQ plane coordinates) in QAM modulation. The QAM modulation system is a system in which phase modulation is performed at a multiple (1 to 8) of 45° , which is a unit angle, in the range of 0° to 360° . That is, symbols that make up the control signal are modulated with a value obtained by multiplying one modulation unit (45°) by one of integers "0", "1", "2", "3", "4", "5", "6" or "7".

The Recommendation V.34 defines modulation patterns for all control signals exchanged on a control channel. In the case of a PPh signal, 8 known symbols are phase-modulated in the order of 11311535 and this is repeated 4 times. In the case of an Sh signal, 8 known symbols are phase-modulated in the order of 13131313 and this is repeated 3 times and then 8 known symbols of an Sh bar signal are phase-modulated in the order of 57575757 and this is sent only once.

The modem apparatus obtains the modulated phase from coordinates of reception symbols in a signal space diagram when reception symbols are QAM-demodulated. Then, when the modulation pattern with which reception symbols are modulated matches the modulation pattern of the PPh signal, the modem apparatus detects that the PPh signal has been received. When the modulation pattern with which reception symbols are modulated matches the modulation pattern of the Sh signal, the modem apparatus detects that the Sh signal has been received.

However, it is sometimes difficult to make a

distinction when there is a shift of oscillation frequency between the calling side and answering side or when coordinates of two consecutive symbols come closer to each other or a phase rotation occurs due to influences of the channel characteristic. For example, it is known that when "1" and "3" are repeated as in the case of quadrature amplitude modulation on an Sh signal, the reception state becomes such that the coordinates of a reception symbol corresponding to the modulation of "1" come closer to the coordinates of a reception symbol corresponding to the modulation of "3" as shown in FIG.2B. In such a reception state, it is difficult to distinguish whether the reception symbol is "1" or "3". FIG.2C shows a state in which the phase of a reception symbol corresponding to the modulation of "3" further rotates toward the "1" side, and in this way the reception symbols corresponding to "1" and "3" enter into the same quadrant. In such a reception state, it is now difficult to achieve accurate demodulation unless the rotated phase is compensated.

Thus, the conventional way of detecting coordinates on a signal space diagram of reception symbols, determining a modulation pattern of consecutive reception symbols and thereby identifying a control signal (Sh signal, etc.) has a problem that it is difficult to identify a control signal, Sh signal in particular, when coordinates of two consecutive symbols come closer to each other or a phase rotation occurs

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beyond a quadrant boundary. This means that failing to detect an Sh signal in the control channel will result in an AC sequence, thereby producing considerable time losses.

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SUMMARY OF THE INVENTION

It is an object of the present invention to provide a highly reliable modem apparatus, image communication apparatus and communication control method capable of precisely identifying control signals exchanged on a control channel without time losses due to failures in signal detection.

That is, the modem apparatus of the present invention demodulates reception symbols subjected to quadrature amplitude modulation, detects the rotation direction of the reception symbols from two consecutive symbols and identifies a control signal sent at the beginning of the control channel based on the rotation direction of the reception symbols.

BRIEF DESCRIPTION OF THE DRAWINGS

The above and other objects and features of the invention will appear more fully hereinafter from a consideration of the following description taken in connection with the accompanying drawing wherein one example is illustrated by way of example, in which;

FIG.1A is a sequence diagram to exchange an Sh signal at the beginning of a control channel in a full-duplex communication of the Recommendation V.34;

FIG.1B is a sequence diagram to exchange a PPh signal at the beginning of a control channel in a full-duplex communication of the Recommendation V.34;

FIG.2A illustrates states of coordinates of consecutive symbols due to a channel characteristic;

FIG.2B illustrates a case where coordinates of consecutive symbols come closer to each other due to a channel characteristic;

FIG.2C illustrates a case where coordinates of consecutive symbols rotate due to a channel characteristic;

FIG.3 is a partial functional block diagram of a modem apparatus according to an embodiment of the present invention;

FIG.4 illustrates a modulation pattern corresponding to symbol strings of an Sh signal and Sh bar signal;

FIG.5A illustrates the rotation directions of reception symbols on a signal space diagram;

FIG.5B illustrates a state in which two consecutive symbols rotate counterclockwise;

FIG.5C illustrates a state in which two consecutive symbols rotate clockwise;

FIG.6 is a flow chart showing an overall flow for determination of a PPh signal and Sh signal by the modem

FIG.7 is a flow chart for determination of an Sh signal by the modem apparatus according to the embodiment above; and

5 FIG.8 is a functional block diagram of a facsimile
apparatus equipped with the modem apparatus according
to the embodiment above.

10 DETAILED DESCRIPTION OF THE
PREFERRED EMBODIMENTS

With reference now to the attached drawings, an embodiment of a modem apparatus of the present invention will be explained in detail below. The modem apparatus according to this embodiment performs communications based on a communication protocol compliant with the Recommendation V.34 defined by the ITU-T. That is, in a half-duplex communication compliant with the Recommendation V.34, when a communication is started with a control channel, an Sh signal or PPh signal is exchanged.

FIG.3 is a block diagram of the reception system of the modem apparatus according to this embodiment. The transmission system is omitted. In this modem apparatus, a reception signal converted to a digital signal by AD converter 11 is subjected to amplitude adjustment by auto-gain controller 12 and then input to demodulator 13. Demodulator 13 performs quasi-coherent detection

The modem apparatus of this embodiment is provided with Sh detector 23 that detects an Sh signal using vector data of two consecutive symbols stored in first and second vector memories 21 and 22. Here, the PPh detector 20 to detect a PPh signal is not shown.

Sh detector 23 is provided with cross product calculation section 24 that calculates a cross product to detect the rotation direction of vectors of two consecutive symbol and comparison section 25 that compares variation series (detection pattern) 26 in the detected rotation direction of a plurality of consecutive reception symbols with variation series (Sh pattern) 27 in the original rotation direction of the

Here, the algorithm used by Sh detector 23 to identify the Sh signal will be explained in detail.

Now, suppose symbols subjected to quadrature amplitude modulation on the calling side are demodulated precisely on the answering side. In this case, the coordinates of the reception symbols change sequentially as (13131313) (13131313) (13131313) (57575757). This will be explained more specifically with reference to FIG.5. In the case of an Sh signal, detection of the reception symbol of coordinate "1" is followed by detection of the reception symbol of coordinate "3" and the detection of the reception symbol of coordinate "3" is followed by detection of the reception symbol of coordinate "1". This is repeated from the beginning to 24th symbol of the Sh signal. When the Sh signal (3rd symbol string) changes to an Sh bar signal (4th symbol string), detection of the reception symbol of coordinate "3" is followed by detection of the reception symbol of

coordinate "5" and the detection of the reception symbol of coordinate "5" is followed by detection of the reception symbol of coordinate "7".

As shown in FIG.5, the change in the coordinates of reception symbols can be seen as a change in the rotation direction. While the Sh signal is being received (period from the 1st symbol string to 3rd symbol string), rotation (B) and rotation (A) are alternated and on the boundary between the Sh signal and Sh bar signal, rotation (C) takes place, and from that point on rotation (D) and rotation (E) are alternated.

A symbol coordinate at the previous reception and a symbol coordinate at the present reception have a relationship in terms of rotation direction between "clockwise" and "counterclockwise". Since the modulation pattern of symbols making up the Sh signal (Sh bar signal) is known, by continuously monitoring the direction of rotation from a symbol coordinate at the previous reception to a symbol coordinate at the present reception, it is possible to identify whether the signal is an Sh signal or not from a series of variations in the rotation direction.

In the case of the Sh signal in particular, a counterclockwise rotation takes place between the 7th symbol and 8th symbol of the 3rd symbol string, a counterclockwise rotation takes place between the 8th symbol of the 3rd symbol string and 1st symbol of the Sh bar signal and a further counterclockwise rotation

takes place between the 1st symbol and the 2nd symbol of the Sh bar signal. That is, a "counterclockwise" rotation takes place 3 times consecutively. On the other hand, in the case of the modulation pattern of symbols making up the PPh signal, a "counterclockwise" rotation never takes place 2 times consecutively. Therefore, a symbol can be determined as an Sh signal when coordinates of reception symbols at the beginning of a control channel rotate "counterclockwise" at least two times consecutively.

The following cases can be considered as identification conditions of an Sh signal: When (1) a "counterclockwise" rotation is observed twice consecutively, (2) a "counterclockwise" rotation is observed three times consecutively, (3) a series of variations in the observed rotation direction includes a part that rotates "counterclockwise" two times consecutively, (4) a series of variations in the observed rotation direction includes a part that rotates "counterclockwise" three times consecutively, etc.

This embodiment uses a series of variations of immediately preceding 16 symbols as an observation unit and identifies an Sh signal when a part rotating "counterclockwise" two times consecutively appears.

This embodiment uses a cross product calculation to detect the rotation direction between two consecutive reception symbols. By the way, it is also possible to detect the rotation direction between two consecutive

reception symbols using a method other than a cross product calculation and using such a method other than a cross product calculation does not depart from the scope of the present invention.

5 Here, suppose two vectors V1 and V2:

$$V1 = [x1, y1, z1], V2 = [x2, y2, z2]$$

Then, a cross product of vectors V1 and V2 can be expressed by the following expression:

[Mathematical expression]

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$$V1 \times V2 = \begin{vmatrix} i & j & k \\ x1 & y1 & z1 \\ x2 & y2 & z2 \end{vmatrix}$$

When a rotation on the XY plane is considered, the component in the Z-axis direction becomes 0,

$$= \begin{vmatrix} i & j & k \\ x1 & y1 & 0 \\ x2 & y2 & 0 \end{vmatrix}$$

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$$= k \begin{vmatrix} x1 & y1 \\ x2 & y2 \end{vmatrix}$$

$$= k(x1y2 - x2y1)$$

where, i, j, k are unit vectors and especially k is a unit vector in the Z-axis direction.

As a result of the cross product calculation of vectors V1 and V2, when $(x_1y_2 - x_2y_1) > 0$, a counterclockwise rotation takes place between vector V1 and vector V2. When $(x_1y_2 - x_2y_1) < 0$, a clockwise rotation takes place between vector V1 and vector V2.

Since a reception symbol (coordinate) can be expressed by a vector made up of the in-phase component (x) and quadrature component (y), it is possible to know the rotation direction by calculating $(P_xN_y - N_xP_y)$ as a cross product between the coordinate at the previous reception (P_x, P_y) the coordinate at the present reception (N_x, N_y) and determining positive or negative.

Then, the operation regarding the identification of an Sh signal of the modem apparatus of this embodiment in the above configuration will be explained with reference to the flow charts in FIG.6 and FIG.7. FIG.6 is a flow chart of a PPh determination and Sh determination executed every time a symbol is received. In a control channel, the PPh detector to detect a PPh signal and the Sh detector to detect an Sh signal (Sh bar signal) operate in parallel. For example, the PPh detector and Sh detector are operated once every 1/600 sec in synchronization with the sampling timing of the reception signal at AD converter 11 and in the case where a PPh signal is detected within a predetermined time (e.g., 3 sec), the process moves on to PPh reception processing or in the case where an Sh signal is detected, the process moves on to Sh reception processing. In the

case where neither PPh signal nor Sh signal is detected within the predetermined time (e.g., 3 sec), the process moves on to error handling.

In this embodiment, the PPh detector determines
5 whether a pattern of coordinates of predetermined
consecutive symbols received in the past matches the
modulation pattern of the PPh signal or not and in the
case where these two patterns match, the PPh detector
turns on a flag indicating that the PPh signal has been
10 detected.

On the other hand, Sh detector 23 executes the above
described cross product calculation between two
consecutive symbols, finds the rotation direction of the
vectors, stores these rotation directions one by one and
15 when the pattern of variations in the rotation direction
of the stored predetermined past symbols matches the
pattern of an Sh signal and Sh bar signal, the Sh detector
23 turns on a flag indicating that the Sh signal has been
detected.

20 FIG.7 is a flow chart used by Sh detector 23 to
identify an Sh signal. The reception symbols
demodulated by demodulator 13 are stored in first vector
memory 21 and second vector memory 22.

At an Sh determination timing synchronized with the
25 timing at which coordinates of reception symbols (vector
data) are written in memory (S51), Sh detector 23 reads
the previous vector (Px, Py), which is the coordinate
of the previously received symbol and the present vector

(Nx, Ny), which is the coordinate of the presently received symbol from one vector memory that stores the vector data of the two consecutive symbols to be determined this time (S52).

5 Then, Sh detector 23 calculates $(PxNy - NxPy)$ as a cross product between the previous vector (Px, Py) and the present vector (Nx, Ny) (S53). As a result, in the case where the polarity of $(PxNy - NxPy)$ is "positive", Sh detector 23 determines that the rotation is

10 counterclockwise and in the case where the polarity of $(PxNy - NxPy)$ is "negative", Sh detector 23 determines that the rotation is clockwise (S54). In the case of a clockwise rotation, Sh detector 23 branches to step S58 and inserts the determination result this time at the

15 end of the positive/negative data string. In the case where the number of data items making up the positive/negative data string reaches 16 bits, Sh detector 23 discards the oldest data. After confirming that it is not time over yet (S59), Sh detector 23 goes

20 back to step S51 above.

 On the other hand, in the case where it is determined by the processing in step S54 above that the rotation is counterclockwise, Sh detector 23 branches to step S55 and executes pattern matching to identify whether the

25 signal is an Sh signal or not. By comparing the positive/negative data string (detection pattern) with the latest positive/negative determination result obtained this time inserted at the end with the Sh pattern

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the control of the modem apparatus 66 above. RAM 64 serves as a work area for CPU 61 or an area to temporarily save an image signal. Scanner interface 69 provides an interface with a scanner, which is not shown. Printer interface 70 provides an interface with a printer, which is not shown. Modem apparatus 66 performs communication control under instructions from CPU 61. The image communication apparatus to which this modem apparatus 66 is applicable is not limited to a facsimile apparatus.

As shown above, this embodiment is designed to identify an Sh signal based on a pattern of the rotation directions of reception symbols, and therefore even if coordinates of two consecutive symbols come closer to each other due to a channel characteristic, etc. this embodiment can accurately determine the rotation direction if there is a phase shift, however small it may be, and can thereby accurately identify the Sh signal, thus preventing time losses involved in Sh detection errors.

The above described embodiment describes the case of identifying an Sh signal, but in the case of a signal whose modulation pattern is known, it is possible to detect the rotation direction and identify the signal from this pattern.

As detailed above, the present invention can provide a highly reliable modem apparatus, image communication apparatus and communication control method capable of precisely identifying a control signal

exchanged through a control channel without time losses involved in signal detection errors.

The present invention is not limited to the above described embodiments, and various variations and
5 modifications may be possible without departing from the scope of the present invention.

This application is based on the Japanese Patent Application No.2000-099562 filed on March 31, 2000, entire content of which is expressly incorporated by
10 reference herein.

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